



Division of River Engineering
Dept. of Land and Water Resources Engineering

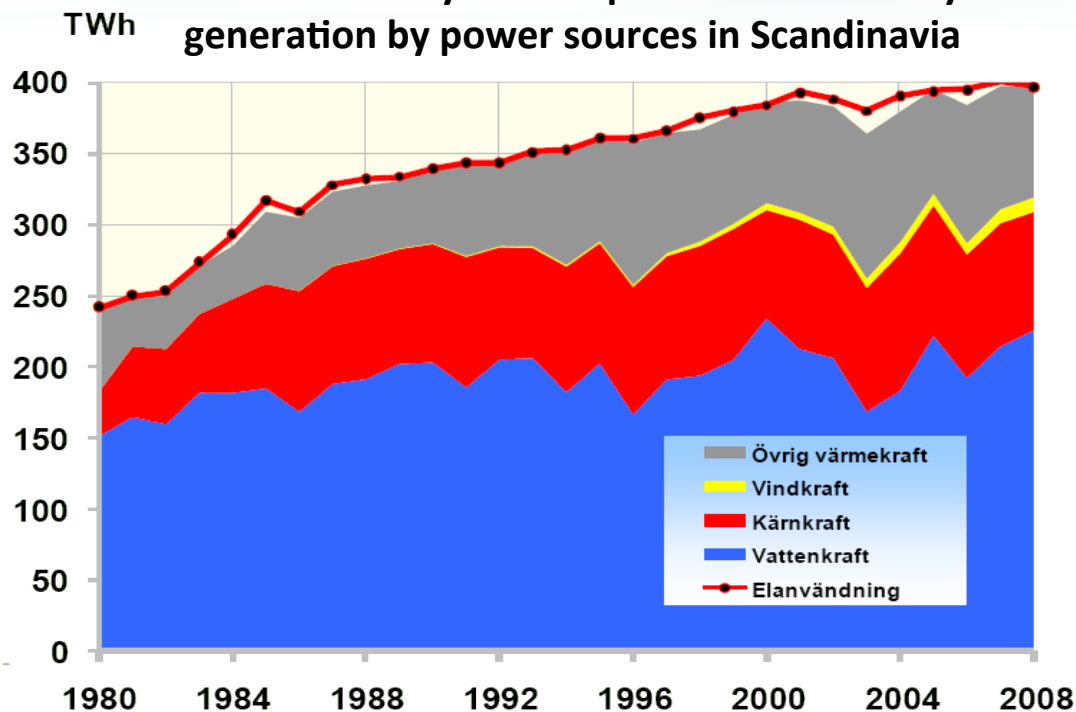
Combined mid- and short-term operational planning of hydropower reservoir systems

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Anders Wörman

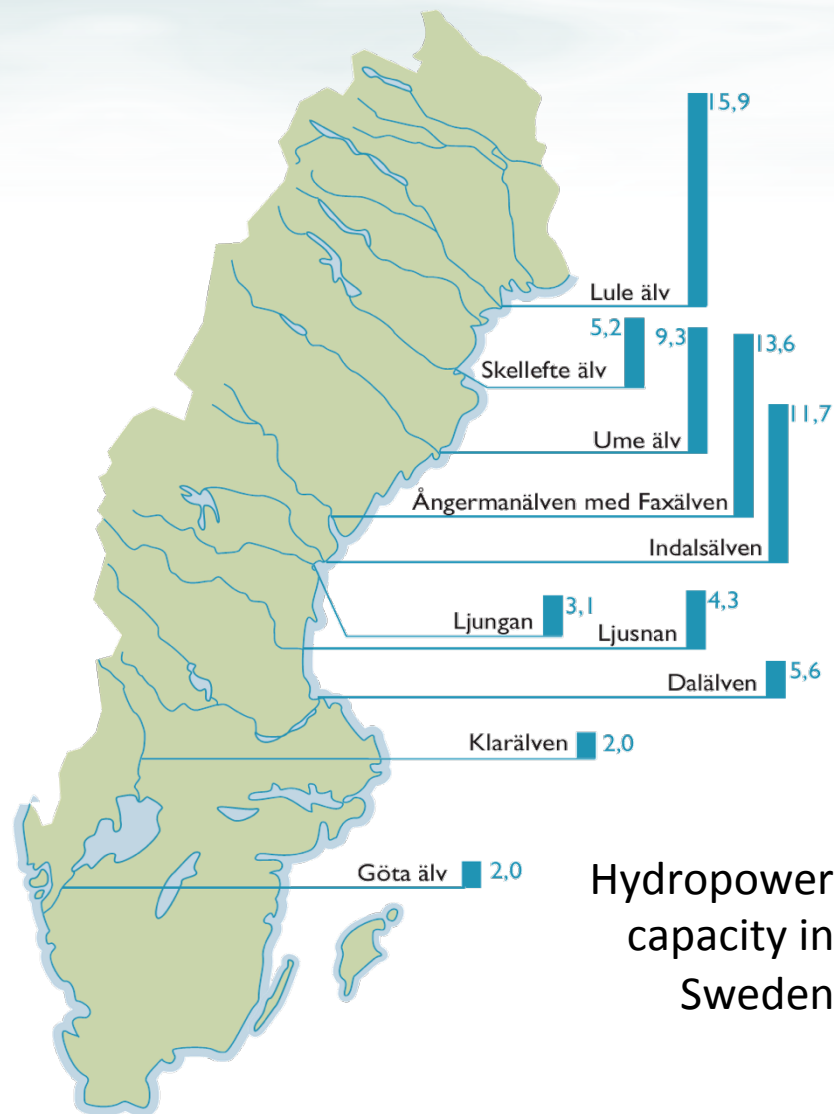
EGU Leonardo 2012

Electricity by power sources in Scandinavia

Total electricity consumption and electricity generation by power sources in Scandinavia



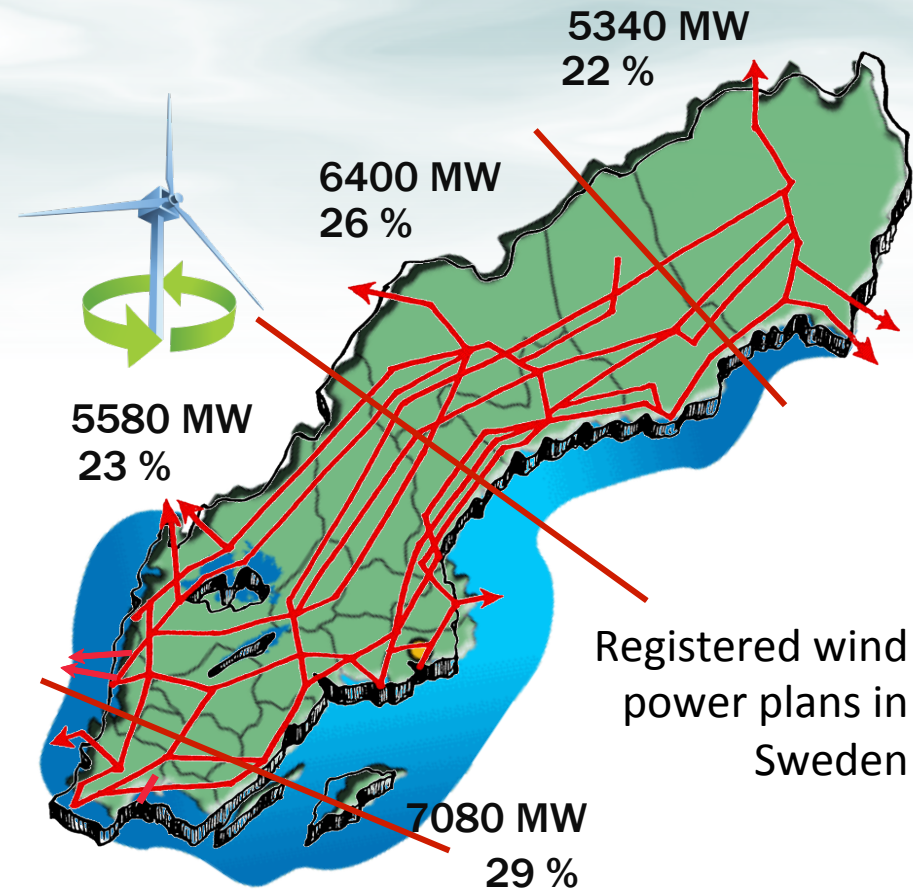
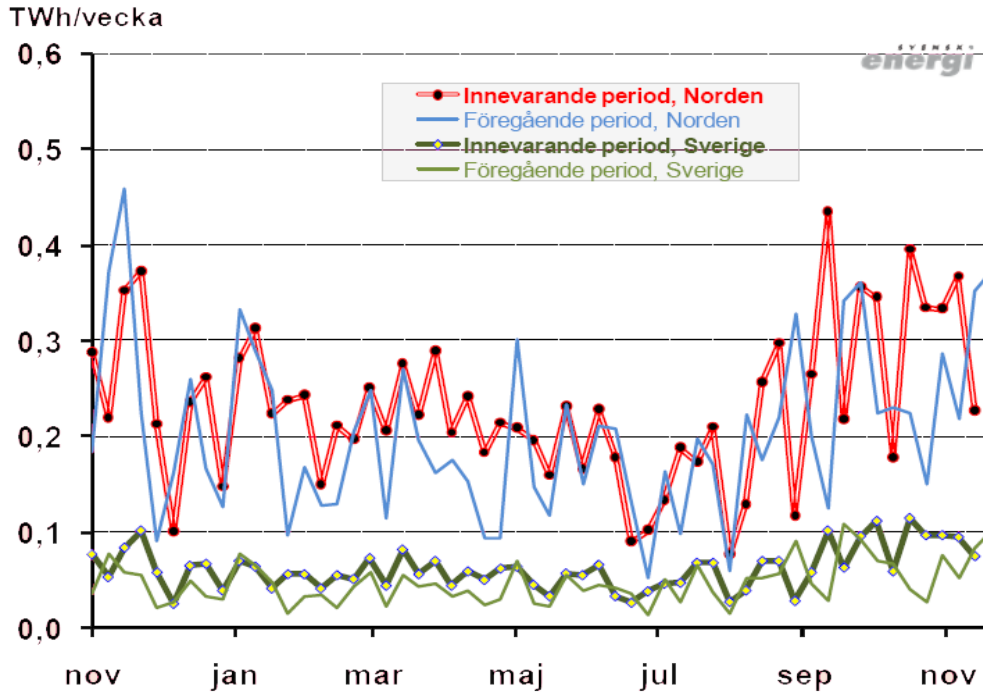
- Hydropower
- Nuclear power
- Thermal power
- Wind power



Hydropower capacity in Sweden

Towards a green energy system

Wind power production per week in Scandinavia and in Sweden, 2010



Intermittent Electricity Production

New quality demands

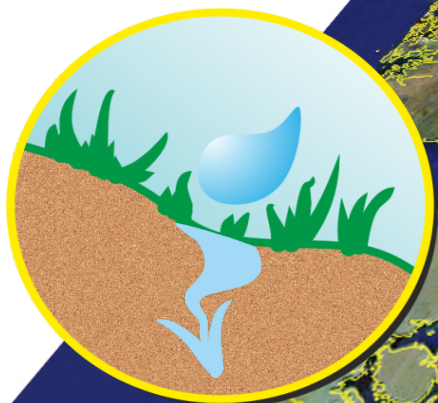
- Improved management of water resources
- Sharper tools for river runoff predictions
- Improved optimization models

Hydropower potential in Sweden

from an unpublished collaboration
with Göran Lindström (SMHI)

**Friction in
atmosphere
– 1763 TWh**

**Rain impact on
ground
– 2 TWh**



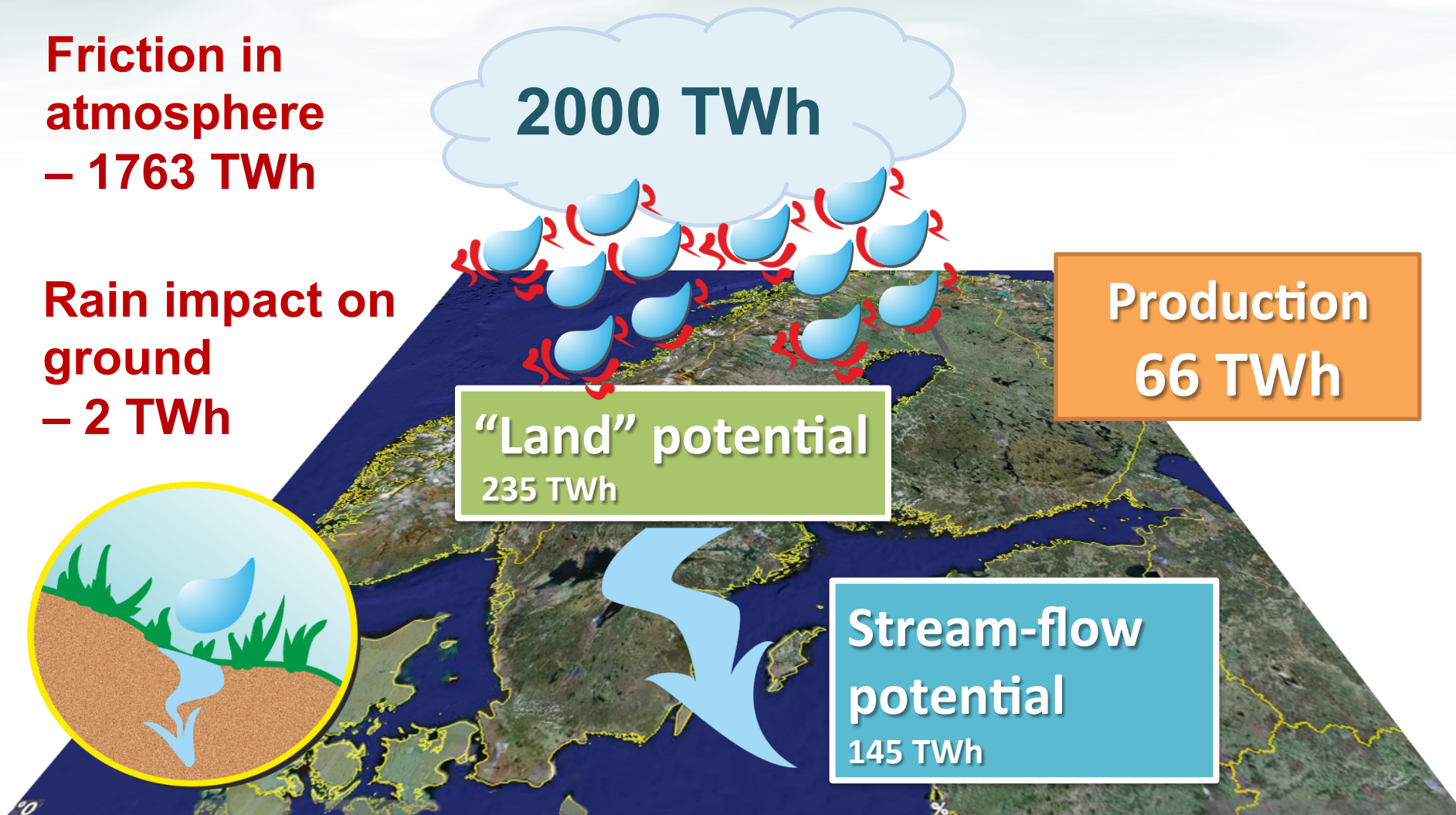
**Percolation in soil
– 90 TWh**

2000 TWh

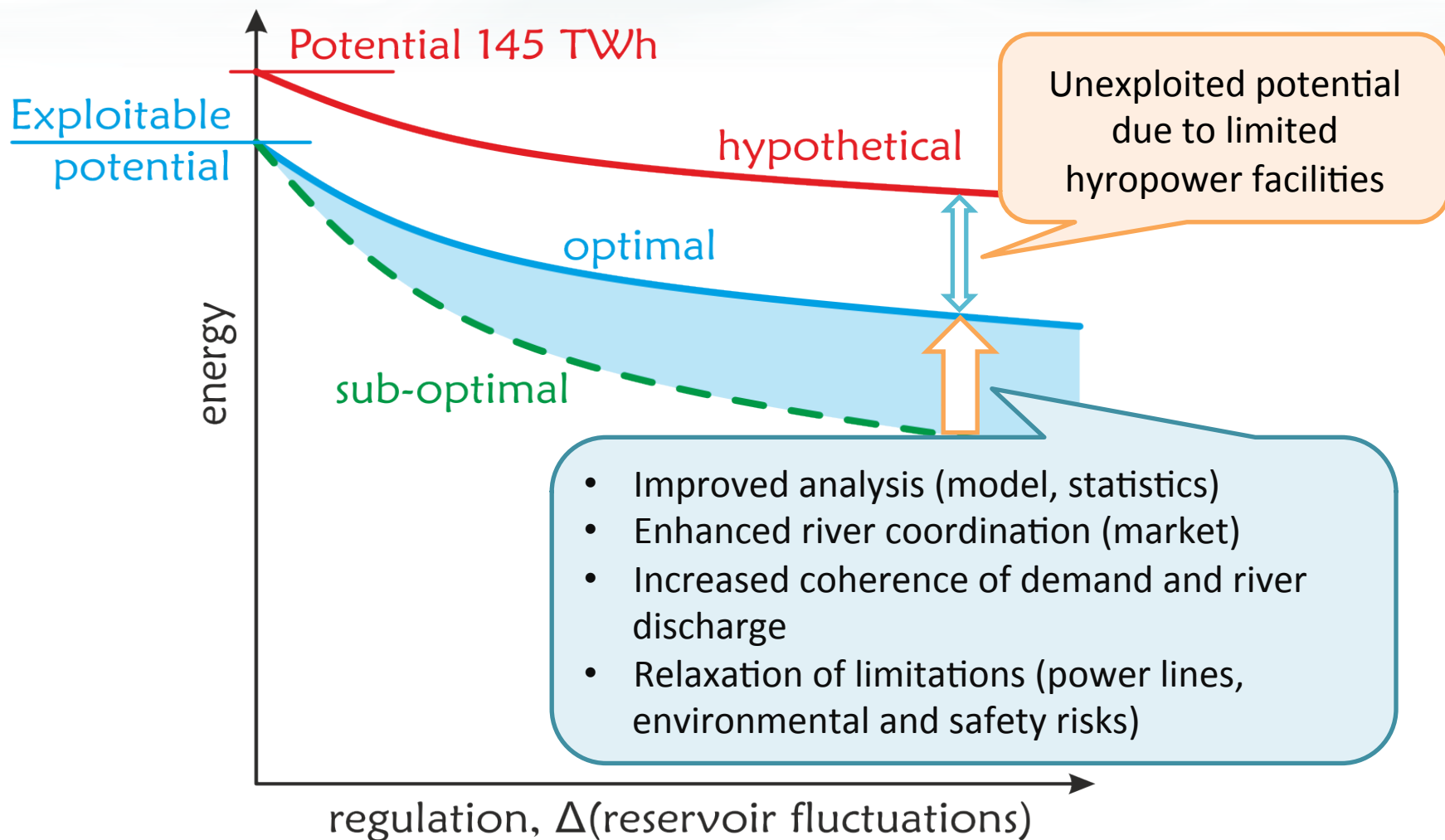
**“Land” potential
235 TWh**

**Stream-flow
potential
145 TWh**

**Production
66 TWh**

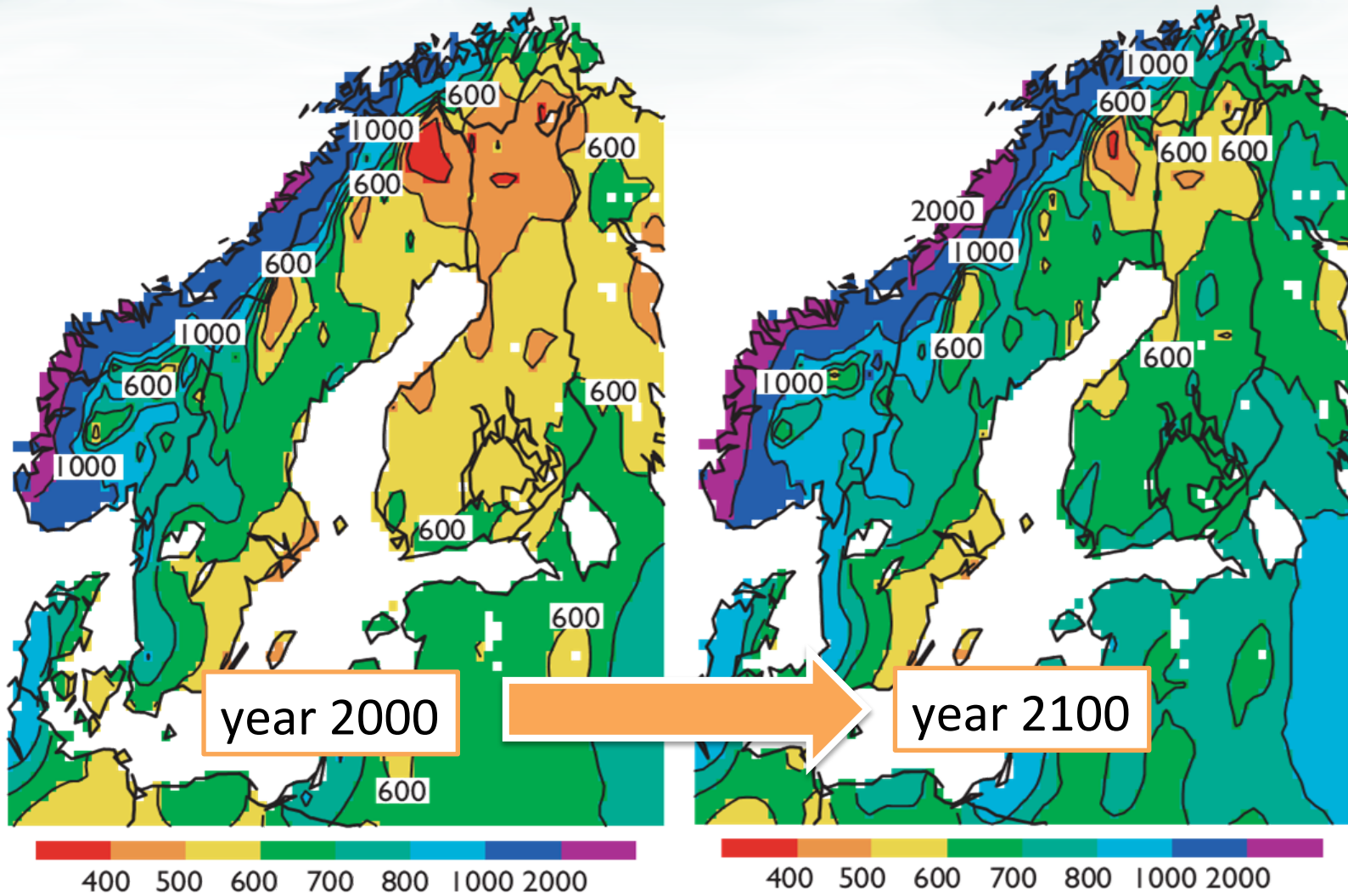


Potential versus suboptimal energy production



Impacts of climate change

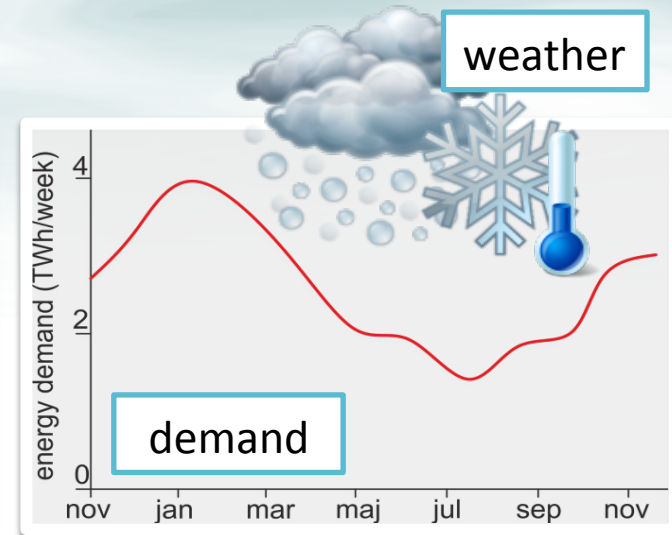
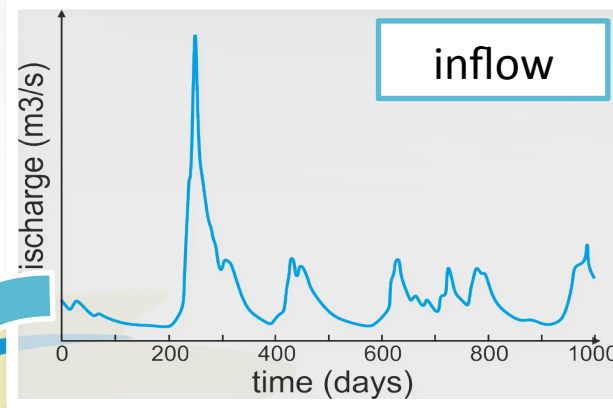
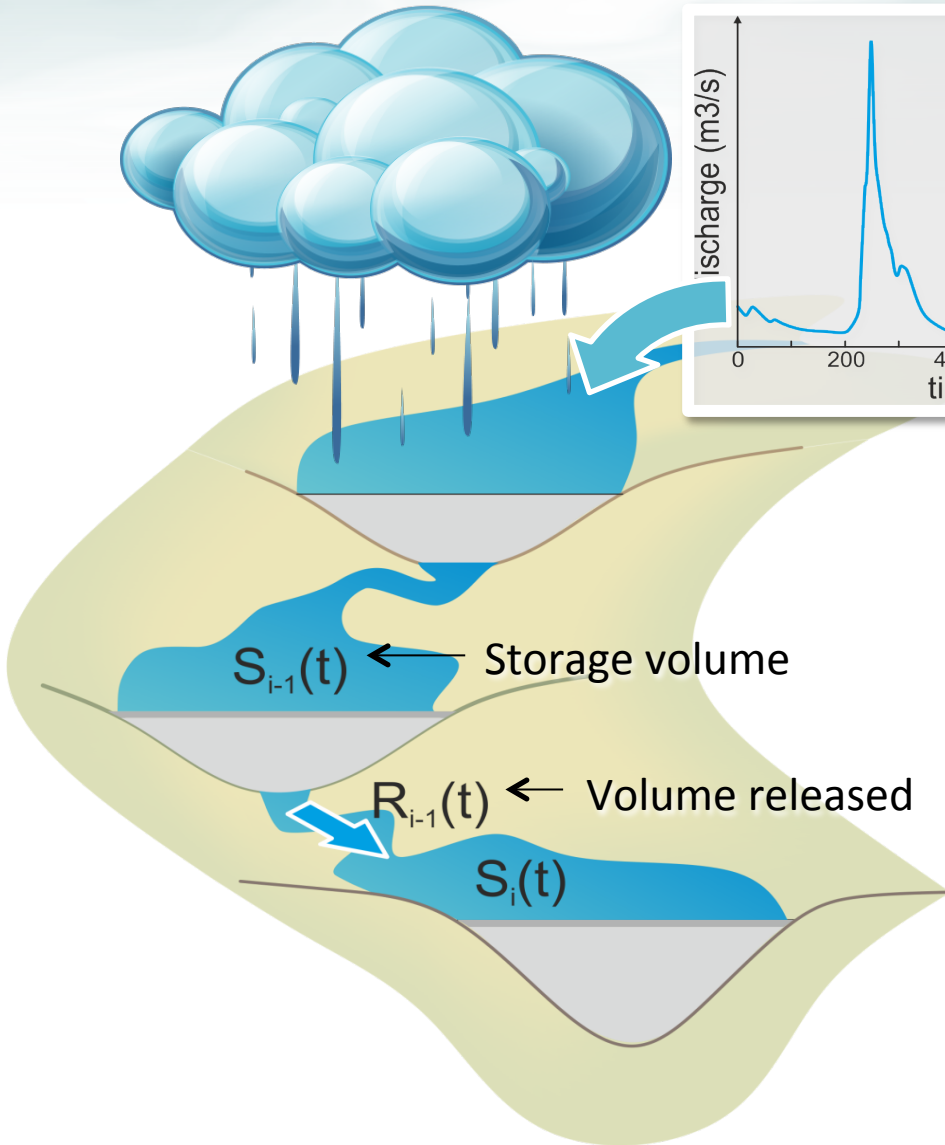
IMPACTS OF CLIMATE CHANGE



Expected increase of surface runoff: +20-40%

from SMHI/SWECLIM

Operation of multi-reservoir systems



Objective Function

Max. Energy output
Min. Flood risk
etc.

Restrictions

Power transmission constraints
Environmental risks
Other constraints

Operation of multi-reservoir systems

The optimization problem

✓ Water balance constraints (system dynamics)

$$S_{i,1}(t) = S_{i,1}(t-1) + Q_{i,1}(t) - R_{i,1}(t) - R_{S,1}(t)$$

$$S_{i,i}(t) = S_{i,i}(t-1) + Q_{i,i}(t) + R_{i-1}(t) - \tau_{i-1} + R_{S,i-1}(t) - \tau_{i-1} - R_{i,i}(t) - R_{S,i}(t)$$

✓ Plant active output constraints

$$P_{i,\min}(t) \leq P_{i,i}(t) \leq P_{i,\max}(t)$$

✓ Plant generation discharge constraints

$$R_{i,\min}(t) \leq R_{i,i}(t) \leq R_{i,\max}(t)$$

✓ Reservoir water-holding capacity constraints

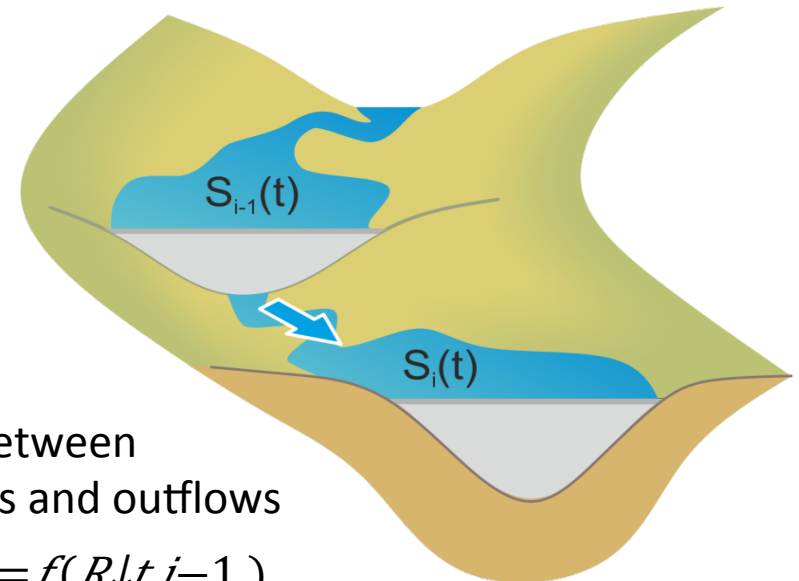
$$S_{i,\min}(t) \leq S_{i,i}(t) \leq S_{i,\max}(t)$$

✓ Objective function

$$J = \text{Max} \sum_{t=1}^T \sum_{i=1}^N E(H_{i,i}(t), R_{i,i}(t))$$



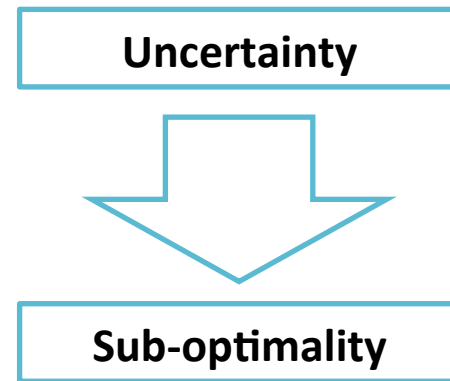
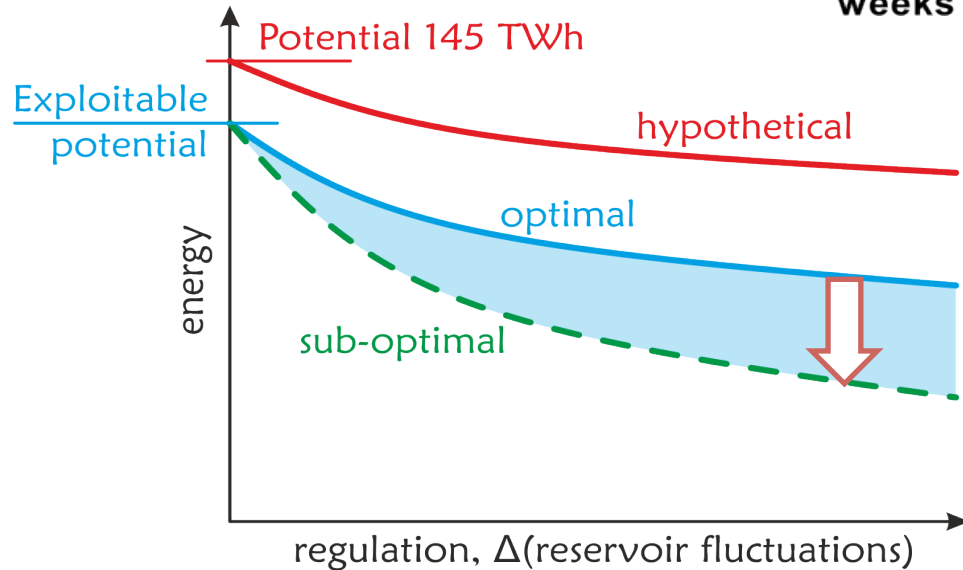
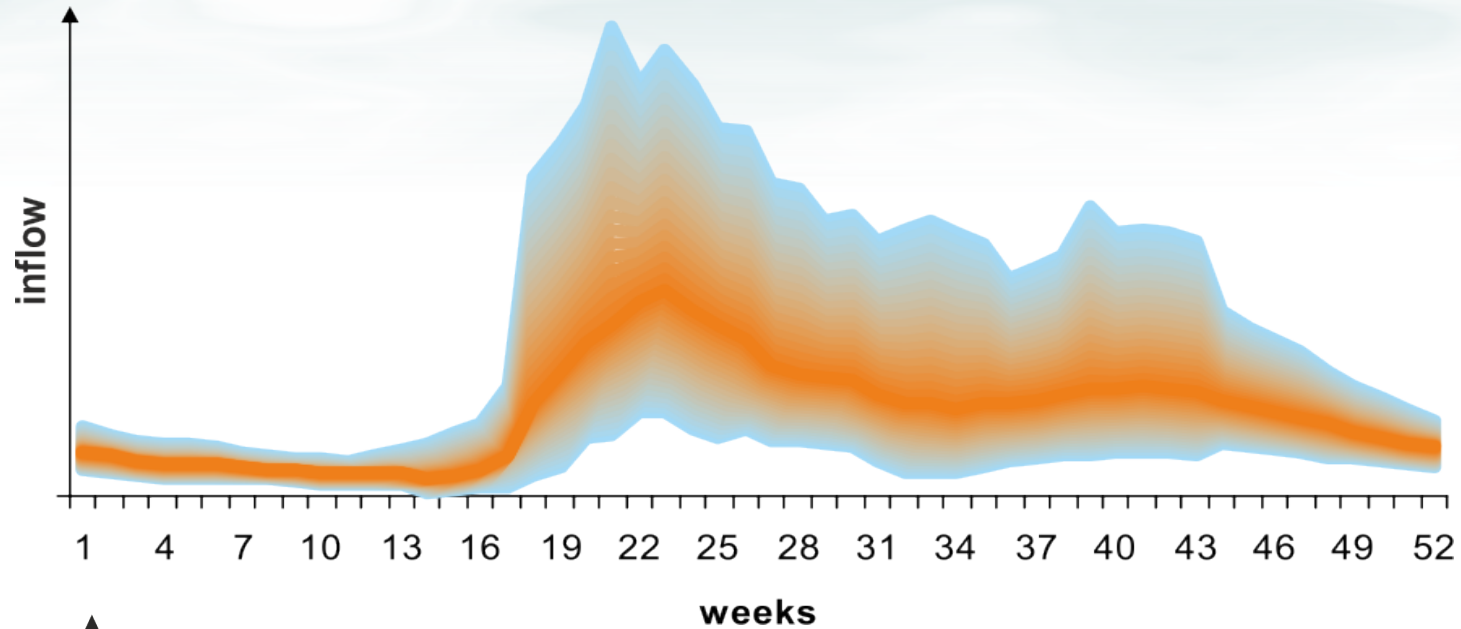
Flow routing
between reservoirs



Link between
Inflows and outflows

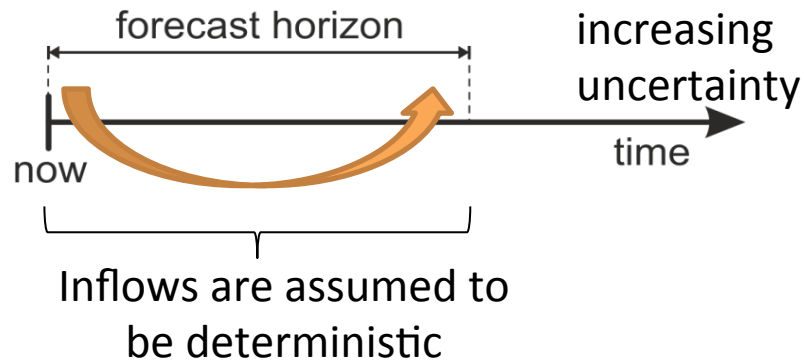
$$R_{t,i} = f(R_{t,i-1})$$

Reservoir operation under forecast uncertainty



Reservoir operation under forecast uncertainty

Deterministic optimization methods (Myopic policies or rolling horizon methods)



Stochastic optimization methods

- Assume inflows are random variables
- Account for different scenarios
- May lead to substantially different operation policies than deterministic methods
- More complex

Mid- and Long- term

Short term

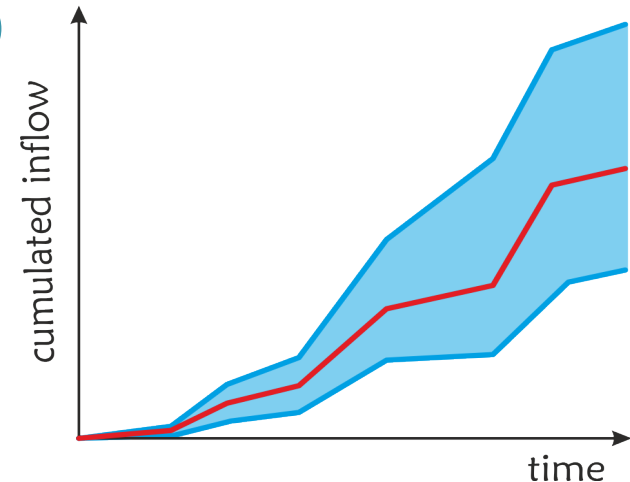
sub-optimality

optimal forecast horizon

forecast horizon

cumulated inflow

time



Operation of multi-reservoir systems

- Optimality equation (Bellman 1957)

$$V_t(S_t) = \max_{R_t} (P_t(S_t, R_t) + \gamma E\{V_{t+1}(S_{t+1}) | S_t\})$$

Value function
Storage

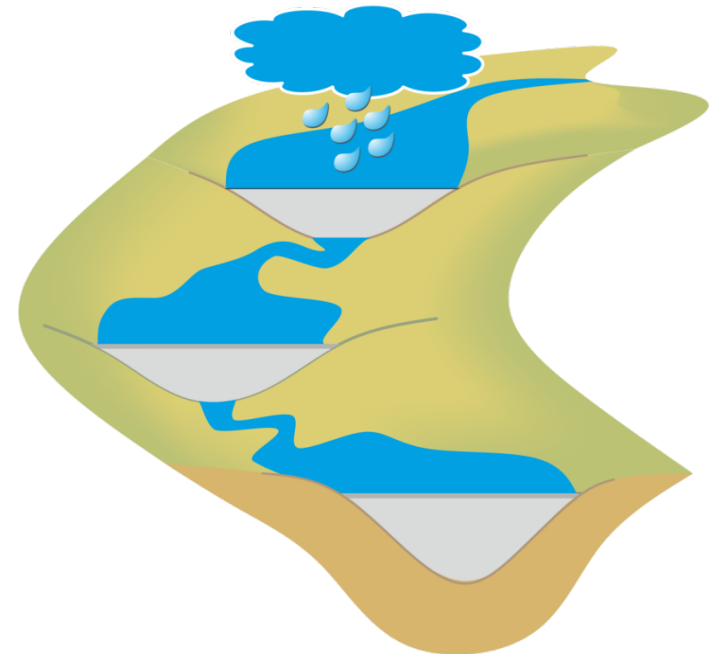
Utility function

Controllable releases

Discount factor

Expectation

- The computational requirements increase exponentially with the number of reservoirs (“curse of dimensionality”)
- Possible solutions:
 - ❑ Approximate dynamic programming (ADP) and reinforcement learning techniques



Approximate dynamic programming (ADP) using function approximators

Approximate dynamic programming

- The value function is expressed as a sum of basis functions

$$V_t(S_t) = \sum_{f \in \mathcal{F}} \theta_{f,t} \phi_f(S_t)$$

- The optimality equation is solved forward in time starting from an initial estimate of the value function
- The coefficients of the value function approximation are determined iteratively via an offline learning process considering a number of inflows scenarios
- Once the value function has been determined, the optimal operating policy is obtained directly from the optimality equation:

$$V_t(S_t) = \max_{\tau} R_t(P_t(S_t, R_t) + \gamma V_{t+1}(S_{t+1}))$$

Generation of stochastic inflow series

GENERATION OF STOCHASTIC INFLOW SERIES

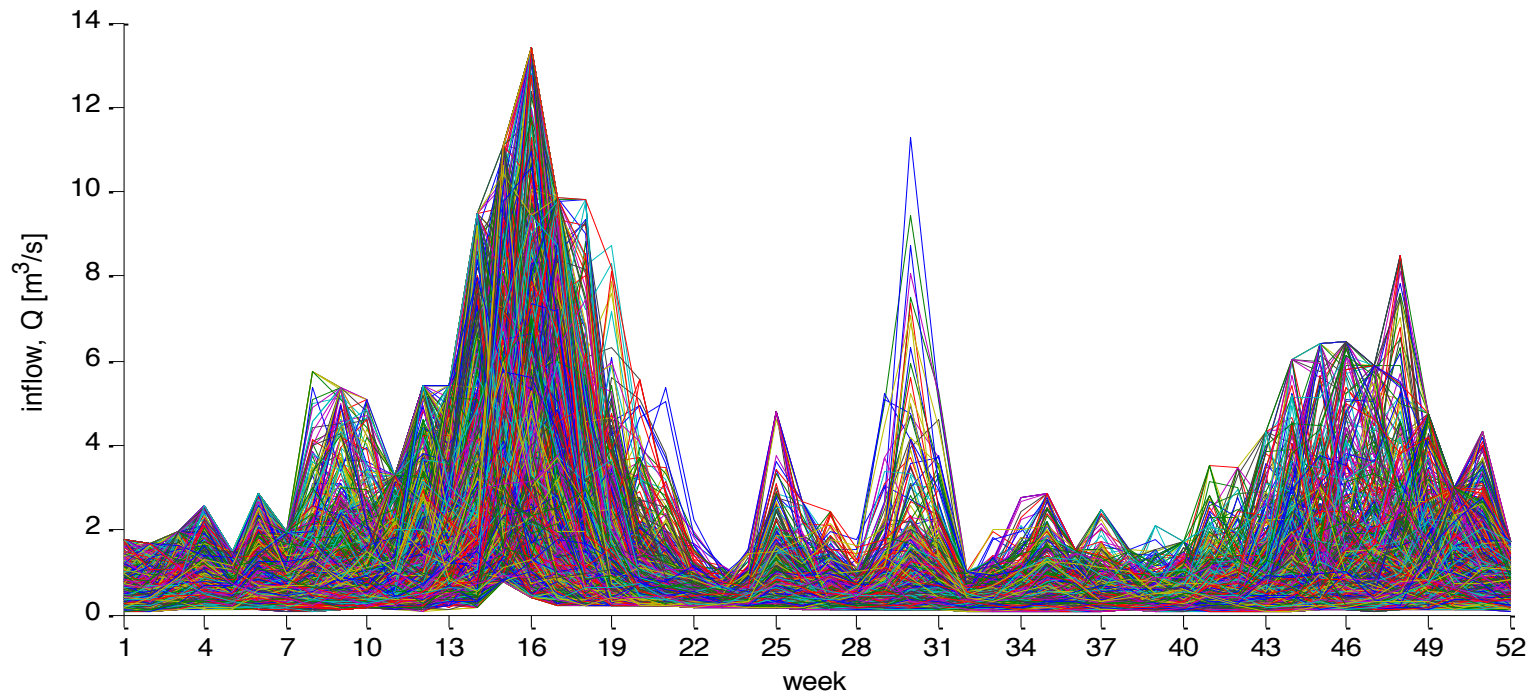
➤ Periodic Autoregressive Model

Standard normal random variable

$$Q(t) \sim N = a_{0,t} + a_{1,t} Q(t-1) \sim N + a_{2,t} \zeta(t) \quad , \quad t=1, 2, \dots, 52$$

Normalized inflow

Synthetic inflow scenarios



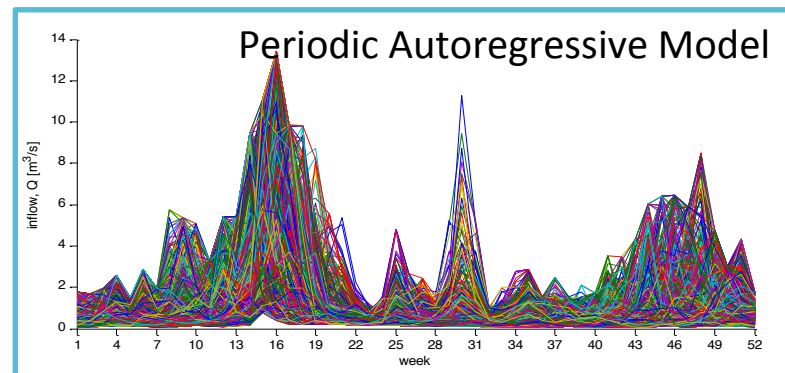
Optimization under uncertainty

An ADP algorithm for stochastic multi-reservoir operation

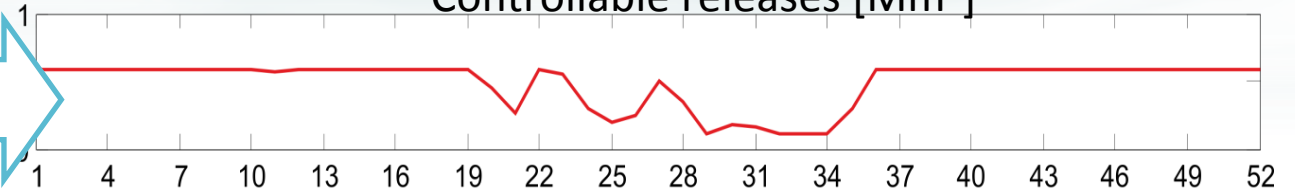
Cyclostationary operational policy

Offline learning process

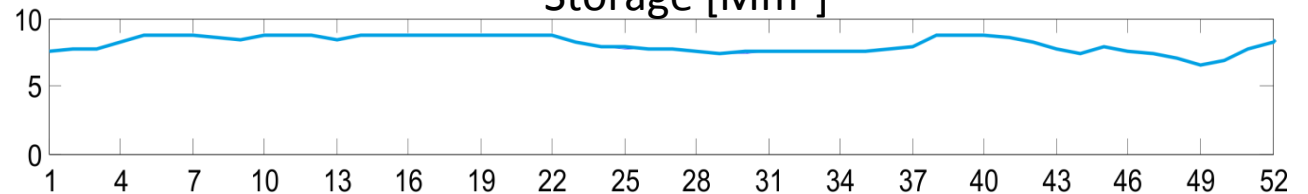
Synthetic inflow scenarios



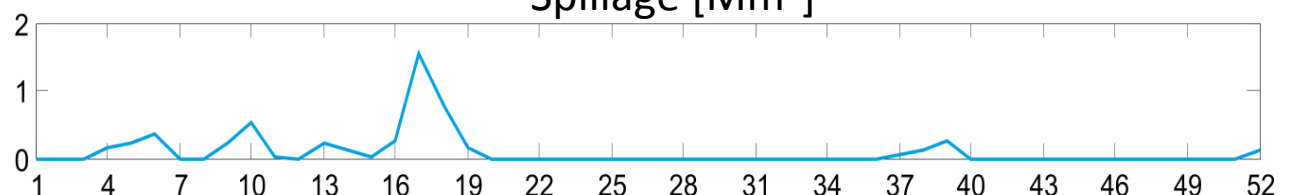
Controllable releases [Mm^3]



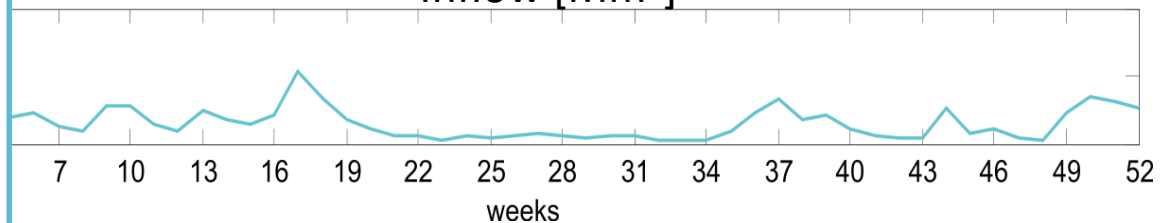
Storage [Mm^3]



Spillage [Mm^3]

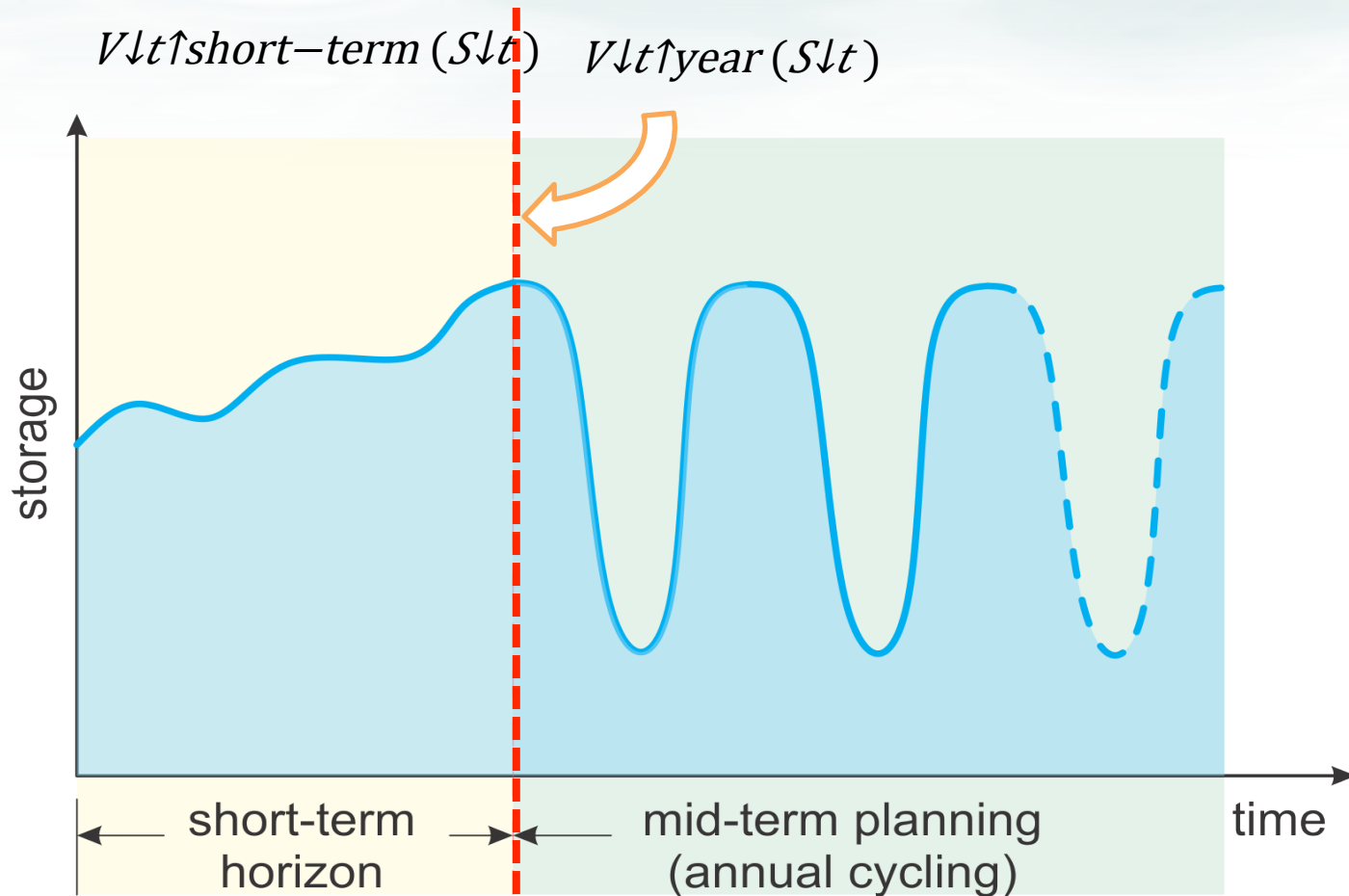


Inflow [Mm^3]



Combined short- and mid-term planning

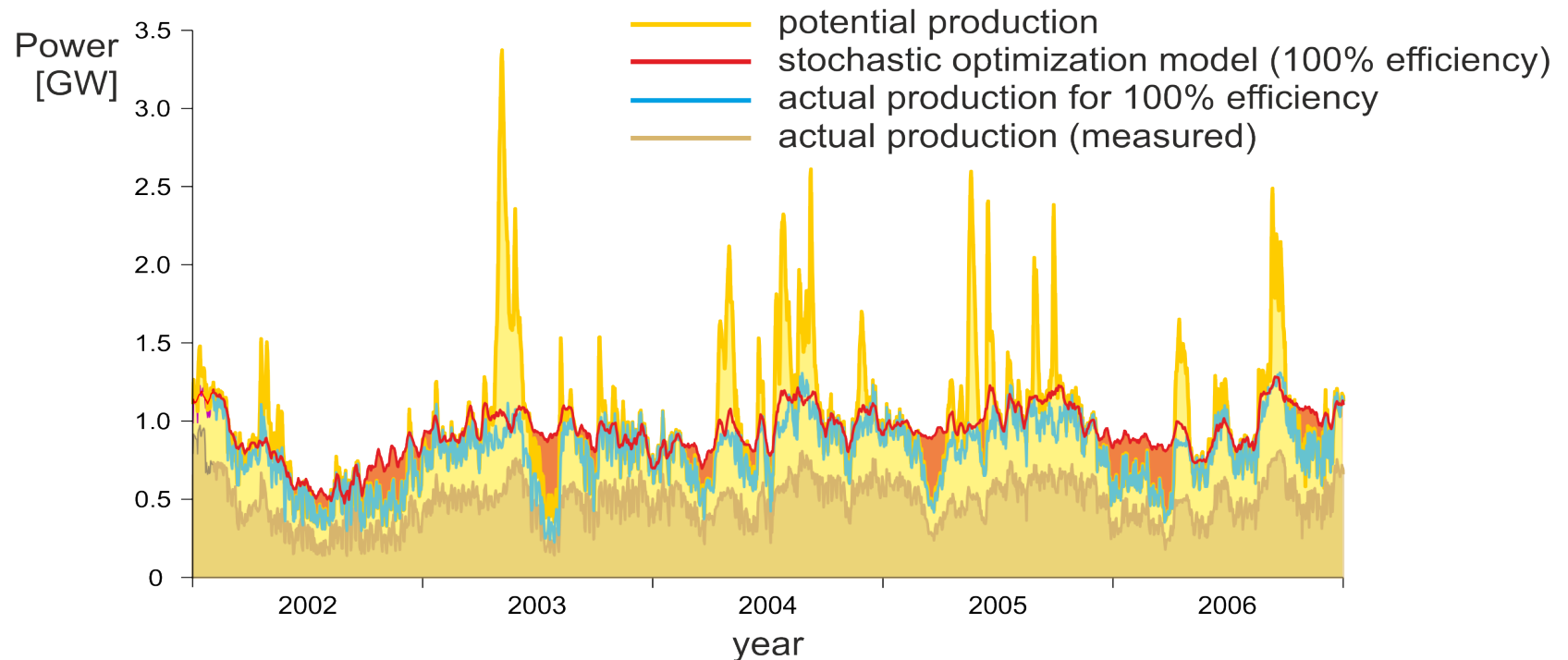
COMBINED SHORT- AND MID-TERM PLANNING



Synthetic inflows are generated assuming the variance of the forecast error increases linearly with time

Case study: The Dal river (Dalälven)

Potential production	8.3 TWh/year
Actual production (measured)	4.2 TWh/year
Actual production assuming 100% efficiency	6.8 TWh/year
Stochastic optimization model assuming 100% efficiency	7.7 TWh/year
Optimization with perfect information assuming 100% efficiency	8.1 TWh/year



Conclusions

- There is potential for significantly increasing the energy production by managing water resources more efficiently
- The efficiency of water management policies is affected by uncertainty and forecast errors
- A new stochastic optimization model for multireservoir systems has been developed
 - ❑ The curse of dimensionality is solved using an approximate dynamic approach
 - ❑ The method combines mid- and short-term planning
- Further model developments will consider:
 - ❑ Different variants of the algorithm
 - ❑ Comparison with other deterministic and stochastic optimization models for small-scale problems
 - ❑ Incorporation of a flow routing model



Thank you!